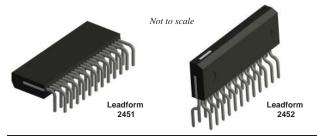




Features and Benefits

- Built-in pre-drive IC
- MOSFET power element
- CMOS compatible input (5 V)
- High-side gate driver using bootstrap circuit or floating power supply
- Built-in protection circuit for controlling power supply voltage drop
- Built-in overtemperature detection circuit (TD)
- Output of fault signal during operation of protection circuits
- Output current 2 A
- Small SIP (SLA 24-pin)

Packages: Power SIP



Description

The SMA6851M inverter power module (IPM) device provides a robust, highly-integrated solution for optimally controlling 3-phase motor power inverter systems and variable speed control systems used in energy-conserving designs to drive motors of residential and commercial appliances. These ICs take an input voltage of 120 VAC, and provide 2A (continuous) output current. They can withstand voltages of up to 250 V (MOSFET breakdown voltage).

The SLA6800M power package includes an IC with all of the necessary power elements (six MOSFETs), pre-driver ICs (two), and flyback diodes (six), needed to configure the main circuit of an inverter. This enables the main circuit of the inverter to be configured with fewer external components than traditional designs.

Applications include residential white goods (home applications) and commercial appliance motor control:

- · Air conditioner fan
- Refrigerator compressor
- · Dishwasher pump

Functional Block Diagram

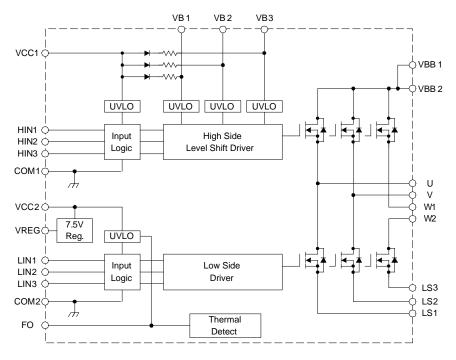


Figure 1. Driver block diagram

High Voltage 3-Phase Motor Driver

Selection Guide

		MOSFET Breakdown	Output Current		
Part Number	Packing	Voltage, V _{DSS} (min) (V)	Continuous, I _O (max) (A)	Pulsed, I _{OP} (max) (A)	
SMA6851M	18 pieces per tube	250	2	4	

Absolute Maximum Ratings, valid at $T_A = 25$ °C

Characteristic	Symbol	Remarks	Rating	Unit
MOSFET Breakdown Voltage	V _{DSS}	$V_{CC} = 15 \text{ V}, I_D = 100 \mu\text{A}, V_{IN} = 0 \text{ V}$	250	V
Logic Supply Voltage	V _{CC}	Between VCC and COM	20	V
Bootstrap Voltage	V _{BS}	Between VB and HS (U,V, and W phases)	20	V
Output Current, Continuous	Io		2	Α
Output Current, Pulsed	I _{OP}	PW ≤ 100 μs, duty cycle = 1%	4	Α
Output Current for Regulator	I _{REG}		35	mA
Input Voltage	V _{IN}		-0.5 to 7	V
Allowable Power Dissipation	P _D	$T_C = 25$ °C	28	W
Thermal Resistance (Junction to Case)	R _{eJC}	All elements operating	4.46	°C/W
Thermal Resistance (Junction to Ambient)	$R_{\theta JA}$	All elements operating	31.25	°C/W
Case Operating Temperature	T _{COP}		-20 to 100	°C
Junction Temperature (MOSFET)	TJ		150	°C
Storage Temperature	T _{stg}		-40 to 150	°C

Recommended Operating Conditions

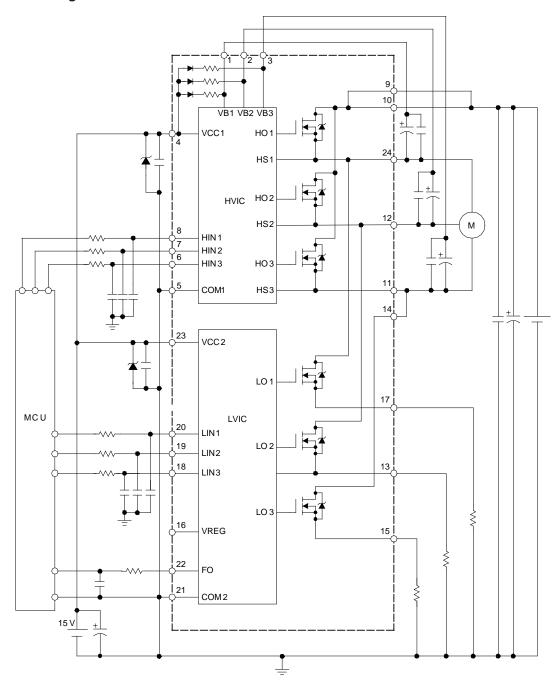
Characteristic	Symbol	Remarks	Min.	Тур.	Max.	Units
Main Supply Voltage	V _{BB}	Between VBB and LS	_	140	200	V
Logic Supply Voltage	V _{CC}	Between VCC and COM	13.5	_	16.5	V
Minimum Input Pulse	T _W (min)		0.5	_	_	μs
Dead Time	t _{dead}		1.5	-	_	μs
Junction Temperature	TJ		_	_	125	°C

All performance characteristics given are typical values for circuit or system baseline design only and are at the nominal operating voltage and an ambient temperature, T_A , of 25°C, unless otherwise stated.





Typical Application Diagram



NOTE:

- All of the input pins are connected to GND with internal pull-down resistors rated at $100 \text{ k}\Omega$, however, an external pull-down resistor may be required to secure stable condition of the inputs if high impedance conditions are applied to them.
- The external electrolytic capacitors should be placed as close to the IC as possible, in order to avoid malfunctions from
 external noise interference. Put a ceramic capacitor in parallel with the electrolytic capacitor if further reduction of noise
 susceptibility is necessary.





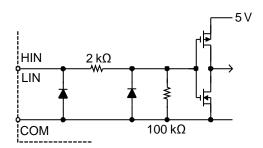
High Voltage 3-Phase Motor Driver

ELECTRICAL CHARACTERISTICS, valid at T_A =25°C, unless otherwise noted

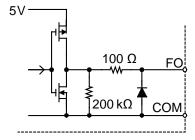
Characteristics	Symbol	Conditions	Min	Тур	Max	Units
Logic Supply Voltage	V _{CC}	Between VCC and COM	13.5	15	16.5	V
Logic Supply Current	I _{CC}	V _{CC} = 15 V, I _{REG} = 0 A	_	4	6	mA
Langet Walterna	V _{IH}	V _{CC} = 15 V, output on	_	2.0	2.5	V
Input Voltage	V _{IL}	$V_{CC} = 15 \text{ V}$, output off	1.0	1.5	_	V
Input Voltage Hysteresis	V _{Ihys}	V _{CC} = 15 V	_	0.5	_	V
lanut Current	I _{IH}	High side, V _{CC} = 15 V, V _{IN} = 5 V	_	50	100	μA
Input Current	I _{IL}	Low side, $V_{CC} = 15 \text{ V}$, $V_{IN} = 0 \text{ V}$	_	-	2	μA
	V _{UVHL}	High side, between VB and U, V, or W	9.0	10.0	11.0	V
	V _{UVHH}		9.5	10.5	11.5	V
Lladon voltogo Look Out	V _{UVHhys}	High side, hysteresis	_	0.5	-	V
Undervoltage Lock Out	V _{UVLL}	Lawrida katawa WOO aad OOM	10.0	11.0	12.0	V
	V _{UVLH}	Low side, between VCC and COM	10.5	11.5	12.5	V
	V _{UVLhys}	Low side, hysteresis	_	0.5	_	V
EO Terminal Output Valtage	V _{FOL}	V 45V	0	-	1.0	V
FO Terminal Output Voltage	V _{FOH}	$V_{CC} = 15 \text{ V}$	4.0	_	5.5	V
Overtemperature Detection Threshold	T _{DH}	V _{CC} = 15 V, no heatsink	130	145	160	°C
Temperature (activation and	T _{DL}		105	120	135	°C
deactivation)	T _{Dhys}		15	25	35	°C
Output Voltage for Regulator	V_{REG}	$I_{REG} = 35 \text{ mA}, T_C = -20^{\circ}\text{C to } 100^{\circ}\text{C}$	6.75	7.5	8.25	V
Bootstrap Diode Leakage Current	I _{LBD}	V _R = 500 V	_	5	10	μA
Bootstrap Diode Forward Voltage	V_{FBD}	$I_F = 0.15 A$	_	1.1	1.3	V
Bootstrap Diode Series Resistor	R _{BD}		17.6	22	26.4	Ω
MOSFET Breakdown Voltage	V _{DSS}	$V_{CC} = 15 \text{ V}, I_D = 100 \mu\text{A}, V_{IN} = 0 \text{ V}$	250	_	_	V
MOSFET Leakage Current	I _{DSS}	V _{CC} = 15 V, V _{DS} = 500 V, V _{IN} = 0 V	_	_	100	μA
MOSFET On State Resistance	R _{DS(on)}	$V_{CC} = 15 \text{ V}, I_D = 1 \text{ A}, V_{IN} = 5 \text{ V}$	_	1.4	1.8	Ω
MOSFET Diode Forward Voltage	V _{SD}	$V_{CC} = 15 \text{ V}, I_{SD} = 1 \text{ A}, V_{IN} = 0 \text{ V}$	_	1.1	1.5	V
MOSFET Diode Recovery Time	t _{rr}	$I_{SD} = 1.5 \text{ A}, \text{ di/dt} = 100 \text{ A/}\mu\text{s}$	_	50	_	ns
Switching Time, High Side	t _{dH(on)}		_	650	-	ns
	t _{rH}		_	100	_	ns
	t _{dH(off)}		_	370	-	ns
	t _{fH}		_	10	-	ns
	t _{dL(on)}	$V_{BB} = 300 \text{ V}, V_{CC} = 15 \text{ V}, I_{D} = 1.5 \text{ A}, 0 \text{ V} \le V_{IN} \le 5 \text{ V}$	_	600	_	ns
Switching Time Low Side	t _{rL}		_	100	_	ns
Switching Time, Low Side	t _{dL(off)}		_	300	_	ns
	t _{fL}		_	10	_	ns







HINx and LINx Terminals Internal Equivalent Circuit

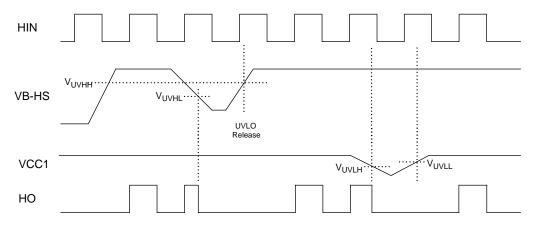


FO Terminal Internal Equivalent Circuit



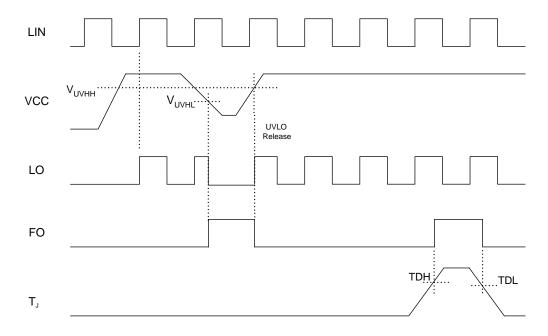


High Side Driver Input/Output Timing Diagrams



After UVLO is released, IC operation is started by the first rising edge of input

Low Side Driver Input/Output Timing Diagrams



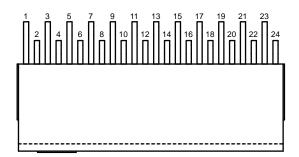
After UVLO is released, IC operation is started by the first rising edge of input

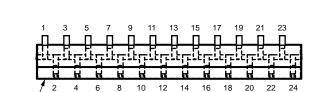


Pin-out Diagrams

Chamfer Side







Leadform 2452

Chamfer on Opposite Side

Terminal List Table

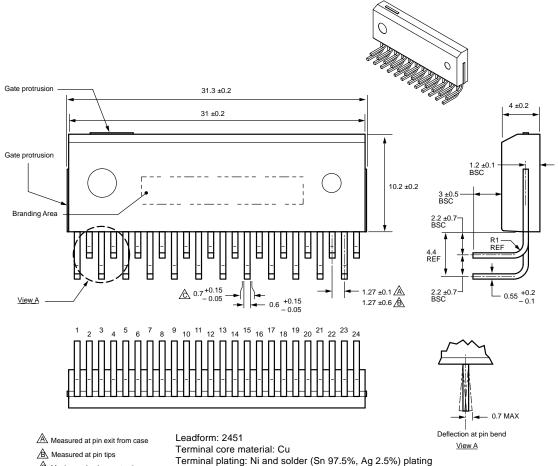
Number Name Function						
	Function					
VB1	High side bootstrap terminal (U phase)					
VB2	High side bootstrap terminal (V phase)					
VB3	High side bootstrap terminal (W phase)					
VCC1	High side logic supply voltage					
COM1	High side logic GND terminal					
HIN3	High side input terminal (W phase)					
HIN2	High side input terminal (V phase)					
HIN1	High side input terminal (U phase)					
VBB1	Main supply voltage 1 (connect to VBB2 externally)					
VBB2	Main supply voltage 2 (connect to VBB1 externally)					
W1	Output of W phase (connect to W2 externally)					
V	Output of V phase					
LS2	Source terminal of V phase					
W2	Output of W phase (connect to W1 externally)					
LS3	Source terminal of W phase					
VREG	Internal regulator output terminal					
LS1	Source terminal of U phase					
LIN3	Low side input terminal (W phase)					
LIN2	Low side input terminal (V phase)					
LIN1	Low side input terminal (U phase)					
COM2	Low side GND terminal					
FO	Overtemperature detection fault-signal output terminal					
VCC2	Low side logic supply voltage					
	VB3 VCC1 COM1 HIN3 HIN2 HIN1 VBB1 VBB2 W1 V LS2 W2 LS3 VREG LS1 LIN3 LIN2 LIN1 COM2 FO					



Package Outline Drawing

Leadform 2451

Dual rows, 24 alternating pins; pins bent 90° for horizontal case mounting; pin #1 in outer row



A Maximum dambar protrusion

Case material: Epoxy resin

Dimensions in millimeters

Branding codes (exact appearance at manufacturer discretion):

1st line, lot: **YMDDT**

Where: Y is the last digit of the year of manufacture

M is the month (1 to 9, O, N, D)

DD is the date

T is the tracking letter

2nd line, type: SMA6861M



Leadframe plating Pb-free. Device composition complies with the RoHS directive.

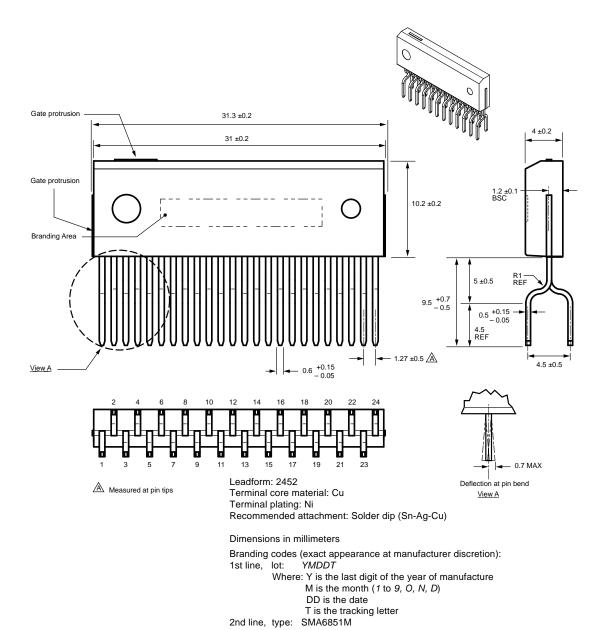




Package Outline Drawing

Leadform 2452

Dual rows, 24 alternating pins; vertical case mounting; pin #1 opposite chamfer side





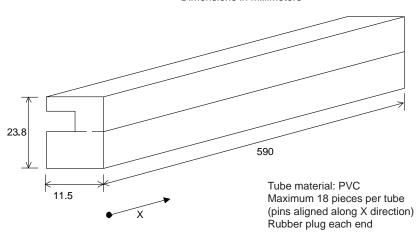
Leadframe plating Pb-free. Device composition complies with the RoHS directive.

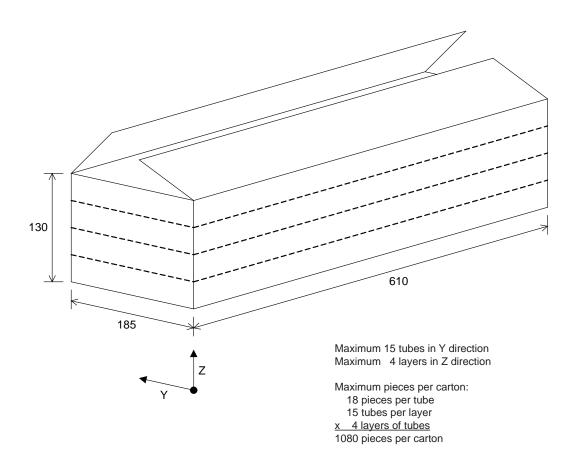




Packing Specification Leadform 2451

Dimensions in millimeters



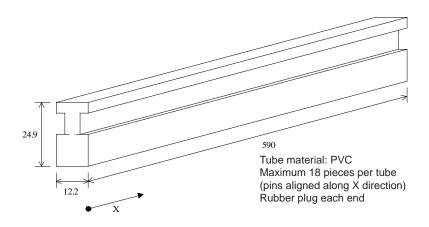


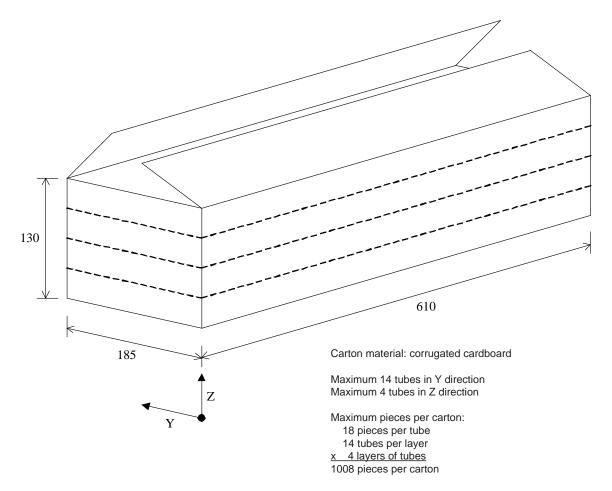




Packing Specification Leadform 2452

Dimensions in millimeters









High Voltage 3-Phase Motor Driver

WARNING — These devices are designed to be operated at lethal voltages and energy levels. Circuit designs that embody these components must conform with applicable safety requirements. Precautions must be taken to prevent accidental contact with power-line potentials. Do not connect grounded test equipment.

The use of an isolation transformer is recommended during circuit development and breadboarding.

Because reliability can be affected adversely by improper storage environments and handling methods, please observe the following cautions.

Cautions for Storage

- Ensure that storage conditions comply with the standard temperature (5°C to 35°C) and the standard relative humidity (around 40 to 75%); avoid storage locations that experience extreme changes in temperature or humidity.
- Avoid locations where dust or harmful gases are present and avoid direct sunlight.
- Reinspect for rust on leads and solderability of products that have been stored for a long time.

Cautions for Testing and Handling

When tests are carried out during inspection testing and other standard test periods, protect the products from power surges from the testing device, shorts between adjacent products, and shorts to the heatsink.

Remarks About Using Silicone Grease with a Heatsink

- When silicone grease is used in mounting this product to a heatsink, it shall be applied evenly and thinly. If more silicone grease than required is applied, it may produce stress.
- Volatile-type silicone greases may permeate the product and produce cracks after long periods of time, resulting in reduced heat radiation effect, and possibly shortening the lifetime of the product.
- Our recommended silicone greases for heat radiation purposes, which will not cause any adverse effect on the product life, are indicated in the following table:

Type		Suppliers
	G746	Shin-Etsu Chemical Co., Ltd.
	YG6260	Momentive Performance Materials, Inc.
	SC102	Dow Corning Toray Silicone Co., Ltd.

Soldering

 When soldering the products, please be sure to minimize the working time, within the following limits:

260±5°C 10 s 380±5°C 5 s

 Soldering iron should be at a distance of at least 1.5 mm from the body of the products

Electrostatic Discharge

- When handling the products, operator must be grounded.
 Grounded wrist straps worn should have at least 1 MΩ of resistance to ground to prevent shock hazard.
- Workbenches where the products are handled should be grounded and be provided with conductive table and floor mats.
- When using measuring equipment such as a curve tracer, the equipment should be grounded.
- When soldering the products, the head of soldering irons or the solder bath must be grounded in other to prevent leak voltages generated by them from being applied to the products.
- The products should always be stored and transported in our shipping containers or conductive containers, or be wrapped in aluminum foil.





High Voltage 3-Phase Motor Driver

The products described herein are manufactured in Japan by Sanken Electric Co., Ltd. for sale by Allegro MicroSystems, Inc.

Sanken and Allegro reserve the right to make, from time to time, such departures from the detail specifications as may be required to permit improvements in the performance, reliability, or manufacturability of its products. Therefore, the user is cautioned to verify that the information in this publication is current before placing any order.

When using the products described herein, the applicability and suitability of such products for the intended purpose shall be reviewed at the users responsibility.

Although Sanken undertakes to enhance the quality and reliability of its products, the occurrence of failure and defect of semiconductor products at a certain rate is inevitable.

Users of Sanken products are requested to take, at their own risk, preventative measures including safety design of the equipment or systems against any possible injury, death, fires or damages to society due to device failure or malfunction.

Sanken products listed in this publication are designed and intended for use as components in general-purpose electronic equipment or apparatus (home appliances, office equipment, telecommunication equipment, measuring equipment, etc.). Their use in any application requiring radiation hardness assurance (e.g., aerospace equipment) is not supported.

When considering the use of Sanken products in applications where higher reliability is required (transportation equipment and its control systems or equipment, fire- or burglar-alarm systems, various safety devices, etc.), contact a company sales representative to discuss and obtain written confirmation of your specifications.

The use of Sanken products without the written consent of Sanken in applications where extremely high reliability is required (aerospace equipment, nuclear power-control stations, life-support systems, etc.) is strictly prohibited.

The information included herein is believed to be accurate and reliable. Application and operation examples described in this publication are given for reference only and Sanken and Allegro assume no responsibility for any infringement of industrial property rights, intellectual property rights, or any other rights of Sanken or Allegro or any third party that may result from its use.

Copyright © 2008 Allegro MicroSystems, Inc. This datasheet is based on Sanken datasheet SSJ-03644





High Voltage 3-Phase Motor Driver

Worldwide Contacts

Asia-Pacific

China

Sanken Electric Hong Kong Co., Ltd.

Suite 1026, Ocean Centre Canton Road, Tsimshatsui Kowloon, Hong Kong

Tel: 852-2735-5262, Fax: 852-2735-5494

Sanken Electric (Shanghai) Co., Ltd.

Room 3202, Maxdo Centre Xingyi Road 8, Changning District Shanghai, China

Tel: 86-21-5208-1177, Fax: 86-21-5208-1757

Taiwan Sanken Electric Co., Ltd.

Room 1801, 18th Floor 88 Jung Shiau East Road, Sec. 2 Taipei 100, Taiwan R.O.C. Tel: 886-2-2356-8161, Fax: 886-2-2356-8261

Japan

Sanken Electric Co., Ltd. Overseas Sales Headquarters

Metropolitan Plaza Building 1-11-1 Nishi-Ikebukuro, Toshima-ku Tokyo 171-0021, Japan Tel: 81-3-3986-6164, Fax: 81-3-3986-8637

Korea

Sanken Electric Korea Co., Ltd.

Samsung Life Yeouido Building 16F 23-10, Yeouido-Dong, Yeongdeungpo-gu Seoul 150-734, Korea Tel: 82-2-714-3700, Fax: 82-2-3272-2145

Singapore

Sanken Electric Singapore Pte. Ltd.

150 Beach Road, #14-03 The Gateway West Singapore 189720

Tel: 65-6291-4755, Fax: 65-6297-1744

Europe

Sanken Power Systems (UK) Limited

Pencoed Technology Park Pencoed, Bridgend CF35 5HY, United Kingdom Tel: 44-1656-869-100, Fax: 44-1656-869-162

North America

United States

Allegro MicroSystems, Inc.

115 Northeast Cutoff Worcester, Massachusetts 01606, U.S.A. Tel: 1-508-853-5000, Fax: 1-508-853-7895

Allegro MicroSystems, Inc.

14 Hughes Street, Suite B105 Irvine, California 92618, U.S.A.

Tel: 1-949-460-2003, Fax: 1-949-460-7837



